

Density Based Traffic Controller(By Using IoT)

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Abstract—The job involves determining a splendid traffic signal plan based on thickness, in which the location of the traffic sign varies and the thickness of each blend can be detected. Gridlock is a big concern in many metropolises around the world, and the proposal to move from manual to stationary to robotic structures with complex cut-off results in an impairment in traffic time if only one heading is operating. The present traffic hailing mechanism is a stable setup that is unlikely to be effective. To stimulate this difficult situation, we have set up a smart traffic light plan. Compared to normal, a greater thickness on one side of the mix requires It was given a longer green period We, therefore, propose a design that determines the distance of traffic between green and red lights in the region. This is enhanced with the PIR (proximity Infrared sensors). The microcontroller displays the bright green light season only when space is adjusted (Arduino). Sensors detected on the roadside can identify vehicles and forward the data to the microcontroller, which determines whether the flank is open or whether the sign lights are modified. By obtaining isolates, we demonstrated the technique of this switch.

I. INTRODUCTION

The problem. The capacity of individuals is damaged and the general Finally, Gridlock is a major public in our day-to-day activities so many hours of work are spent on signs. The driving forces behind this rotting jam are a great many vehicles, a precarious foundation, and an arbitrary distribution of the grassy structure. Taking a circular route increases the option when motors stay, Taking into account that there is no productive result in the use of the huge amount of daily resource in oil and diesel. Likewise, these problems should be removed or at least degraded.

Being caught in gridlocks can be the most common issue you meet on the board. When the number of private cars on the road increases, so does the number of cars on the road. Driving away every day is incredibly weakening, leading to frustration with the public transport system. A traffic lighting system that manages traffic signal timing and identifies traffic signal violators is required to keep up with increasing building activities in major cities.

Using IoT, a traffic regulator based on thickness with default ID is implemented. The framework then discerns the traffic volume at the crossing and adjusts the situation of a traffic light to reduce the road traffic blockage while also recording the number of entries.

Another contributor to multiple illegal traffic offenses is the inadequate lighting system, as people are constantly waiting for the signal period which has a lower vehicle thickness than other existing densities.

Staying away from extreme gridlocks is critical in the current situation. The traffic thickness is a key aspect of this planned traffic light scheme rather than strict regulation of the signs at a fixed time. This proposal relies on sensor detection by the Arduino UNO and similar devices, investigation, and calculation of conditions, and provides power to the LEDs according to the time of the code control. This framework, in its entirety, senses the presence and strength of a vehicle on a given track.

II. PROPOSED SYSTEM

A system of hand signals used by traffic police officers as well as traffic lights and markings regulates the traffic light in the present situation. A nearly identical and coordinating training program must be implemented by driver-

authorization specialists to ensure that those who use engine vehicles understand road rules and the actions expected or encouraged to take when a specific control system is available. For example, the stop signals also have a red background and are octagonal, each traffic light system is designed and applied according to rules. The plan's principles allow the driver to easily and reliably see the sign on the street in the visual field. The use of standard shadings and form helps to identify and choose the best solution.

Traffic signals are currently designed to function in several ways following a defined loop with a fixed time delay when switching from one sign into another, creating an undesired and ineffective clogging on the one hand while other routes remain open. The method we propose recognizes the traffic volume on each route and thus guides the sign planning situation. The IR trans beneficiaries are counting the obstacles and considering traffic density on a given road. Answer to a regulator unit that decides as and when necessary. The model is based on the concept of changing the deferment of the traffic signal based on the number of vehicles through the relegated lane segment. The number of vehicles in the sensor-protected zone is calculated by four sensors on all four sides of a four-way route.

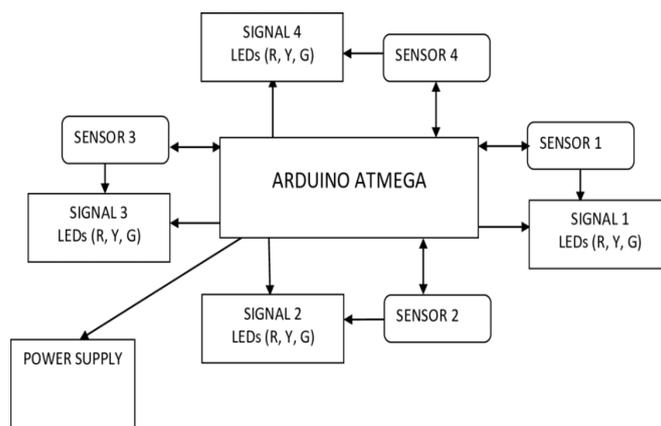


Figure 1: Block Diagram

III. COMPONENTS

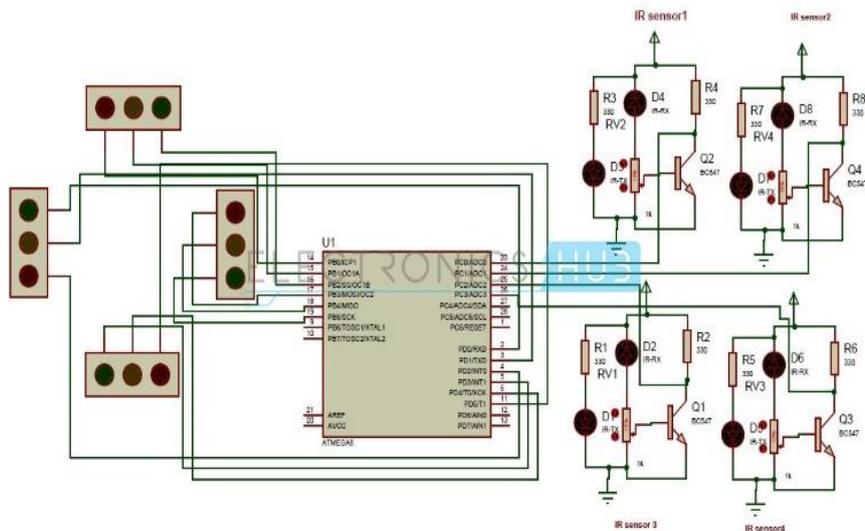
	Arduino Mega 2560 & Genuino Mega 2560	x	1
	Ultrasonic Sensor - HC-SR04 (Generic)	x	4
	5 mm LED: Red	x	5
	5 mm LED: Green	x	4
	5 mm LED: Yellow	x	4

IV . CIRCUIT PRINCIPLE

At the heart of this traffic, the scheme is the microcontroller. The PORT C (PC0, PC1, PC2, and PC3) microcomputer connects IR sensors while the PORT B and PORT D link traffic signals. In any event, the specific sensor yield is logical 0 if traffic is on the road. After we agree with these IR sensor rates, we need to write the

traffic management program.

If either of these sensors returns a rationale of 0, it is necessary to give the green sign and the red sign any remaining ways. To look for traffic, we have always to track the IR sensors.



Circuit Components:

- ATmega8 controller
- PCB board
- IR sensors -4
- LED's-12(4-red,4-green,4-yellow)
- 12v Battery or adaptor
- Serial cable
- Connecting wires

A thickness-based traffic light control system This circuit consists of 4 infrasonud sensors, an ATmega8, and 4 traffic lights.

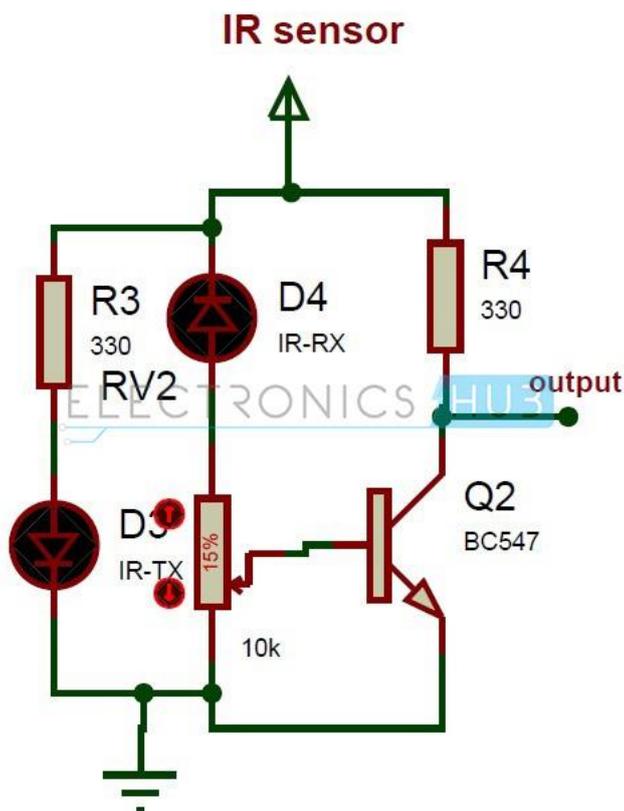
The LED appears to be the IR transmitter. The IR transmitter periodically transmits IR beams. The operating voltage of this IR transmitter is between 2 and 3 volts. These rays are invisible to the naked eye. Infrared rays. In either case, the camera shows these IR rays.

The IR transmitter transmission transmits IR waves that are obtained from the IR. If the IR beneficiary accepts IR beams, it is normally very resistant to super ohms, while the obstruction is minimal when it rejects IR beams. The working voltage of the IR recipient is raised by two to three volts.

We must position the IR pairs to allow an IR beneficiary to receive the IR beams if a block is put in front of them. The transmitted IR beams contact the object and when we use force they bounce back to the IR receiver.

LEDs may be used rather than traffic signals (RED, GREEN, YELLOW). In a typical gridlock rush hour system, you must sparkle the LEDs at once. If the traffic density is high on a specific track, the green LED shines on this track, while the red LEDs shine on excellent track conditions.

We allow the traffic to be delayed for one second in either way, in a typical rush-hour gridlock scenario.



In the diagram above the IR sensor circuit is shown. If the IR transmitter is affected, a 330-ohm resistor is employed to reduce the voltage. The detection distance was changed by a potentiometer. The semiconductor authority has sent us feedback. This sensor gives the advanced output.

Traffic signaling system circuit based on operating density: step by step guidance

- Attach a 12V battery or socket to the improvement board.
- Switch inventory on.
- Keep programming switch sw2 to burn the ATmega8 microcontroller to program mode.
- Infrared four PORT C sensors attached.
- Connect PORTS B and D with the LED.
- Arrange the equivalent of this LED in a pattern like a traffic signal.
- On each lane, install one IR sensor.
- You are now going to see a regular traffic scheme based on a time assumption.
- Now, if you put a deterrent before an IR sensor, the framework is going to permit traffic by flashing GREEN light through that particular direction.

Finally, the power supply to the board will be switched off.

V. METHODOLOGY

In this relationship, the microcontroller is the core component. The only gadget that monitors and controls the whole interaction. We will use a regulator in Atmega328 format, also called ARDUINO UNO. The Arduino module is an open-source plug-and-play controller. The regulator includes the advanced converter, the generator of pulse duration, and EEPROM memory.

The ESP8266 is an affordable Wi-Fi module with TCP/IP functions. The module is used to provide the web worker with details. The module only requires the legal agreement of AT orders for communication with the web worker. Previously, Arduino was revised for order sets for the board.

The solar panel and windmill voltage are significantly higher than the basic referral voltage of the controller. Simply stated, the working voltage of the regulator surpasses the fundamental reference voltage.

In our case, it is half the voltage provided by the regulator. To reduce the produced voltage, we need a voltage divisor before it is forwarded to the regulator.

The working voltage of the controller is inadequate to directly drive the hand-off, so the relay loop can be regulated by a driver circuit. The driver circuit requires a high-low signal to power the hand-off module. The transmission module is often used as a switch to control the AC load. The AC axis is supplied by the inverter.

Only the LCD and ESP modules are fastened after the Arduino microcontroller is charged. Show them on the LCD, then, directly via them. The knowledge is transferred to the worker in a crucial timeframe. The regulator also monitors the customer contribution from the cloud to track the AC load.

VI. RESULTS AND DISCUSSION

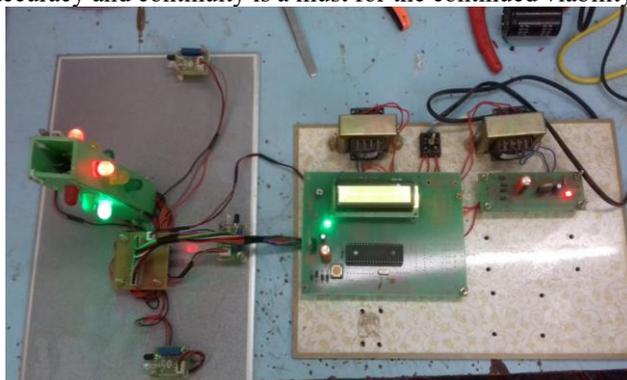
The model sketches the guideline for the adjustment of the delay of the signal depending upon the number of vehicles on the road. The number of vehicles that pass through the sensor-protected area is composed of four sensors on four sides of the four-lane road.

We use IR sensors to substitute frameworks to plan an intelligent traffic light system. The IR sensor consists of both an IR and an IR receiver (photodiode).

These transmitters and collectors are mounted on the same roadside at a certain distance. The IR sensor identifies and transmits the data to the device as the vehicle moves through these IR sensors. A computer that allows you to monitor a microcontroller. The microcontroller determines the number of vehicles and the main brilliant potential for LEDs depending on the thickness of the vehicle. The LED will glow for a longer time than average if the thickness is larger or vice versa. Initially, the traffic signals are set at 5 seconds, with a total contact delay of 20 seconds. This is the focus of the whole installed system. The microcontroller is attached to LEDs and infrared sensors. The total number of IR sensors required is four, and LEDs are 12. This connects these to any two ports of the microcontroller.

Perhaps low-level IR sensors do not work well for a flagging device for long distances. We may depend on ultrasound or radar for wide range configurations.

- Then the effects of the stray signal can be transmitted to the microcontroller and can change the sensor readings.
- A daily check of model accuracy and continuity is a must for the continued viability of the model.



VIII. CONCLUSION

Our country needs a proper transport board structure as 384 road accidents occur regularly in India. A high-level framework in this activity is designed to reduce blockage and unwanted gridlock time. Dissemination of schedule openings will lead to the irritating disarray of traffic based in particular on the importance of vehicle load on multi-crossing tracks using the invention in that field.

IX . REFERENCES

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