

Design and Fabrication of Electric scooter

Veeramanikandan¹, Hari Hara Sudhan², Hritik B³, Karthick P⁴, Kishore SM⁵

¹Assistant Professor, Department of Automobile Engineering, Karpagam College of Engineering, Coimbatore-641032, Tamilnadu, India

^{2,3,4,5} UG scholars, Department of Automobile Engineering, Karpagam College of Engineering, Coimbatore-641032, Tamilnadu, India

Abstract-

With the massive hobby in electric automobile technology, all extraordinary kinds of MOTORS are shifting towards green focus, such as the bike. As time progresses, the investigations on the motorbike evolved to an even extra complex model as the model want for you to consist of the dynamics of the motorbike at excessive pace. Relatively, few works of the literature discovered on an electric scooter modelling. Therefore, this paper ambition to develop an electric scooter that represents a model of scooter with each kinematics and dynamics of the scooter incorporated in the model. The advanced model is then tested for the velocity tracking and the range travelled to evaluate the performance.

Keywords- Electric scooter, kinematics and dynamics of the scooter, motorbike

I. INTRODUCTION

An electrically driven scooter is a battery-powered vehicle that is mostly intended for people with limited mobility. It is commonly used for those who have trouble walking or standing for extended periods of time. Scooters come in three basic designs: those designed for indoor use, those intended for outdoor use, and those that can be used both indoors and outdoors. An electric scooter differs from a motorised wheelchair in where the wheelchair is usually built for indoor use and costs significantly more. An electric scooter can also have two, three, or four wheels. It does not emit toxins since it relies on rechargeable batteries. A traditional electric scooter will require a pair of batteries, which are renewable. The amount of time an electric scooter will operate on a single charge is highly dependent on the type and capacity of its battery. The most common place batteries are advertised to last for around 8 hours and 20-30 miles before needing charging. Some people are hesitant to purchase an electric scooter because they believe it would be difficult to use. In reality, once you get the hang of it, the manipulate console makes it pretty easy. Electric scooters now have more powerful brake mechanisms, making stopping easy and comfortable. The brake continued to develop so that the rider could connect with the throttle as easily as possible.

A. Electric Vehicle

An electric vehicle (EV) is one which uses an electric motor to generate power instead of an internal-combustion engine that consumes a combination of gas and fuels. As a result, along with car promises to be a viable replacement for today's technology vehicle, as well as a feasible solution to the issues of rising pollution, global warming, depletion of natural resources, and so on. Despite the fact that the concept of electric car has been here for a long time, it has sparked a great deal of interest in the last decade as a result of the growing carbon emissions and other effects on the environment of gasoline-based automobiles.

B. Vehicle Types

Any type of vehicle may typically be equipped with an electric powertrain.

1) *Plug-In Electric Vehicle*: A plug-in electrically powered car (PEV) is a vehicle that can be recharged from any external source of electricity, such as electrical outlets, and that uses the energy contained in rechargeable battery packs to drive or assist in spinning the wheels.

2) *Hybrid Evs*: A hybrid electric vehicle incorporates a traditional (often fossil-fuel-powered)

powertrain with some type of electrical propulsion. Since their launch in 1997, over eleven million hybrid electric vehicles have been delivered worldwide as of April 2016. Japan has the highest number of hybrid market places in the world. By 2013, the electric industry accounted for more than 30% of all new luxury vehicle deliveries and about 20% of all new passenger cars sales, including kei cars. Norway came in second with a hybrid market share of 6.9% of new vehicle purchases in 2014, led by the Netherlands with 3.7 percent.

3)

II. METHODOLOGY



Fig.1 Methodology

A motor is a mechanical system that converts electric energy into mechanical force. "Every time a contemporary carrying conductor is put in a magnetic field, it practises a mechanical force" says the DC motor's operating principle.

Our operations of the business are generally defined by using the blocks as follows:

- i) Battery
- ii) Controller
- iii) Electric Motor

A. Battery

Four sealed lead acid rechargeable batteries with a capacity of 12 volts and 7 ah are used, which can then be linked in parallel. It generally stores the produced electrical power and uses it to power the motor. A battery has a good terminal called cathode and a weak terminal called anode. When connected to an outside circuit, the terminal marked high quality has a higher electric ability capacity, while the terminal marked poor has a lower electric ability power. Electrons can migrate and provide energy to an outside unit. Batteries that are rechargeable can be recharged several times.

B. Controller

To perform its responsive, comparative, and correction functions, an Electronic Controller employs electrical warnings and automated algorithms. Operational Principles An electronic sensor (thermocouple, RTD, or transmitter) mounted on the size position sends a signal to the controller on a continuous basis. The electric motor's velocity can be varied using this controller.

C. Electric Motor

The strength of an electric motor in a vehicle, like that of most vehicles, is estimated in kilowatts (kW). A hundred kW is approximately equal to 134 horsepower, but electric vehicles can produce full torque over a larger range of RPMs. As a result, the output of a vehicle with a 100 kW electric motor outperforms that of a vehicle with a 100 kW internal combustion engine, which can only provide its maximum torque within a narrow range of engine speeds. During the process of converting electric energy to mechanical energy, energy is lost. Approximately 90% of the battery's capacity is converted to mechanical strength, with the potential losses inside the motor and drivetrain. Direct current (DC) power is usually fed into a DC/AC inverter, which converts it to alternating current (AC) energy, which is then connected to a three-phase AC motor. DC vehicles are widely found in electric trains, forklift trucks, and a few electric cars. In a few cases, conventional motors are used first, followed by AC or

DC. Various motor models have been introduced in recent production vehicles, such as induction automobiles in Tesla Motors and eternal magnet devices in the Nissan Leaf and Chevrolet Bolt.

III. EXPERIMENTAL SETUP

A. BLDC Electric Hub Motor

The wheel hub motor (also known as a in-wheel motor, hub motor, wheel hub force, or wheel motor) is an electric motor that is integrated into the hub of a wheel and concurrently drives it.

An additionally known as a brushless DC electric motor (BLDC motor or a BL motor) and a synchronous DC motor, symphony cars powered by modern direct (DC) power from an inverter or switching power supply that produces power in the form of a modern alternation motor (AC). The synchronous cars supply electricity in the form of a section of each engine through an electric closed motor. The controller supplies the engine winding pulses of the day that regulate the engine speed and torque.

Brushless motors are made in the same way as permanent magnet synchronous motors (PMSMs), and they're often switched reluctance motors or induction (asynchronous) motors.

Excessive energy-to-weight ratio, excessive rpm, electronic power, and low preservation are all advantages of brushless motors over brushed motors. Brushless cars can be used in a variety of areas, from computing peripherals (disc drives, printers), hand-held control devices, and automobiles ranging from model planes to automobiles.



Fig.2 BLDC Hub Motor

B. Electronic Throttle Controller

An electric bike's velocity controller is an electrical circuit that not only regulates the speed of an electric motor but also acts as a dynamic brake. The power from the battery box is used by this controller unit to operate the motor.

Electronic throttle control (ETC) is a vehicle generation that replaces a mechanical linkage by electronically linking the accelerator pedal to the throttle.

A typical ETC system consists of three main components:

- i) an acceleration pedal module (preferably with two or more independent sensors),
- ii) A throttle valve that can be opened and closed using an electric motor (also known as an electric driven or virtual throttle body (ETB))
- iii) A powertrain or engine control module (PCM or ECM).

The benefits of automated throttle control are widely overlooked by most drivers because the aim is to keep the car's electric characteristics smoothly consistent regardless of triumphing circumstances, such as altitude, engine temperature, and accent loads. Electronic throttle control is now operating behind the scenes to increase the advantage at which the riding pressure will perform equipment adjustments and resolve the drastic torque changes involved with rapid accelerations and decelerations.

1) Plug:

1. Red, Black, Blue: Speed Regulator 1-4V Throttle (Red: +5V, Black: -, Blue: Signal Wire)
2. Yellow, black: brake

3. RedBlue:KeySwitch
4. YellowBlue:Motorconnections.
5. Red&Yellow:Brakelight
6. Red&Black(smallcable):Charger
7. Red&Black(bigcable):Batteryconnections.
8. RedBlack(smallcable):indicatorlight

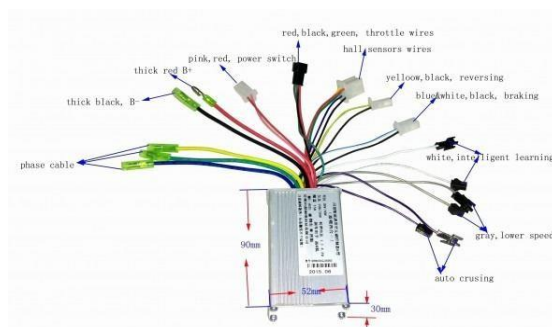


Fig.3 Electronic Throttle Controller

C. Sealed Lead Acid Battery

Researchers produced a maintenance-free lead-acid battery that can work in any place in the mid-1970s. The liquid electrolyte is gelled and sealed into moistened separators. During free discharge and changes in ambient pressure, safety valves allow for venting.

Two lead-acid systems originated as a result of extraordinary industry demands: the small sealed lead-acid (SLA), also known as the Gel cell, and the large valve-regulated-lead-acid (VRLA). The two batteries are quite close. Engineers would argue that the term "sealed lead-acid" is misleading since no rechargeable battery can be fully sealed.

With the exception of flooded lead-acid batteries, both SLA and VRLA batteries have a low over-voltage ability to prevent the battery from exceeding its energy capacity at any point in the charging cycle, as excessive charging could cause gassing and water depletion. As a result, these batteries are unable to be charged to their maximum potential. Sealed lead-acid batteries use lead-calcium rather than lead-antimony to reduce dry-out.



Fig.4 Sealed Lead Acid Battery

D. Drum Brake

A drum brake is a form of brake that uses friction to stop vehicles by pressing outward against a revolving cylinder-shaped element known as the drum brake. Because of its lightweight construction, consistent overall efficiency, high braking electricity, and clean set up of parking gadgets, drum brakes are commonly used in medium and large passenger cars. As the car is driving for miles, the pneumatics system applies torque to the cam, which drives the brake shoes closer to the brake drum, and the braking torque produced between the brake drum and the shoes stops the engine. The standard drum brake shape, on the other hand, has some flaws. For starters, the friction

pressure in the friction plate is not distributed evenly. Furthermore, since brake clearance prohibits the friction plate from perfectly aligning with the brake drum in the braking system, only partial contact happens inside the friction plate. As a result, it deteriorates the interaction circumstances between both the drum and the friction plate, intensifies neighbourhood wear, and decreases the friction plate's carrier life.

IV. Result AND DISCUSSION

Step(3)

To find maximum torque on each wheel

$$T1 = R_{fw} * (D \div 2)$$

$$= 104.467 * [(25.4 * 10^{-2}) / 2]$$

$$T1 = T2$$

$$= 13.26 \text{ Nm}$$

$$\text{Total torque on both wheel} = 26.5 \text{ Nm}$$

Step(4)

To find minimum Speed of wheel to move the

vehicle $\text{Speed of Wheel} = \text{vehicle speed} \times \text{Circumference of Wheel}$

$$= 10 \text{ Km/hr} * (3.14 * 254 \text{ mm})$$

A. REQUIRED POWER TO DRIVE ELECTRIC MOTOR

Step(1)

Average load acting on the vehicle is as follows

$$\text{Average weight of person (From BMC Public Health Research 2005)} = 60 \text{ kg}$$

$$166667 \text{ mm/min} * 797.56 \text{ mm/rpm}$$

Step(5)

To find minimum power of the motor

$$= T_{rw} * \text{rpm} * ((2\pi) / 60)$$

$$=$$

$$= 208$$

Weight of bicycle

$$= 40 \text{ kg}$$

$$= 60 * 9.81$$

$$= 608.22 \text{ N}$$

$$= 40 * 9.81$$

$$= 392.4 \text{ N}$$

$$= 13.26 * 208 * ((2 * 3.14) / 60)$$

$$= 286.84 \text{ Watts} = 287 \text{ Watts}$$

$$\text{Other Miscellaneous load} = 5 \text{ Kg}$$

$$= 5 * 9.81$$

$$= 49.05 \text{ N}$$

$$\text{Total load} = (608.22 + 392.4 + 49.05)$$

$$= 1044.67 \text{ N}$$

Step(2)

To find maximum reaction on each wheel $\text{Force}(F_{fw}) = \text{Force}(F_{rw}) = 1044.67 / 2$

$$= 522.335 \text{ N}$$

To find the reaction on each wheel

$$R_{fw} = R_{rw} = 0.2 * 522.335$$

$$= 104.467 \text{ N}$$

Design

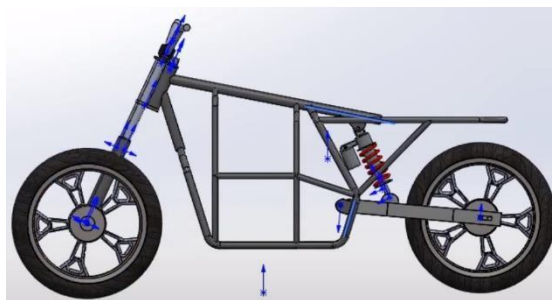


Fig.5E-ScooterFrame

emergency or in a gloomy environment. Batteries are self-charged while solar panels are used.

Since the electrical motor and ICE propulsions will be coordinated, there may be less fuel consumption and a shorter battery charging time (long existence consistent with price). If a single car can save on average 30% of fuel, so using this model of vehicle can save on average 40%-60% of countrywide diesel. And, since the batteries last a long time in accordance with the charge, the energy bill will be saved. Using ICE to charge the batteries is also a viable option. Through these of this kind of car, the durability and convenience of the purchaser can be improved. Lithium-ion batteries can be charged by idling or running an ICE during vehicle propulsion, or by using the solar charging device mentioned.



Fig.6E-ScooterFrame

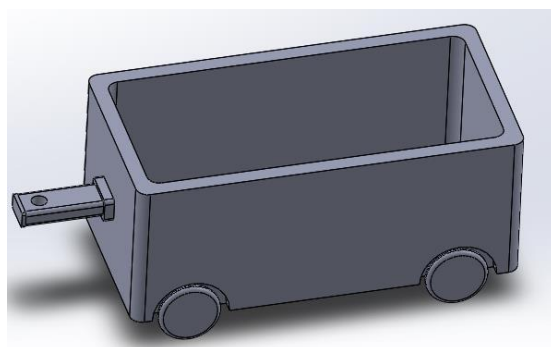


Fig.7 Attachment

V. CONCLUSION

Self-contained charging The current hybrid scooter has been modified into an electric scooter. It is fitting for all cities and roads in the United States of America, whether they be made of cement, gravel, or ashes. This scooter is less expensive, easier to manufacture, and can be commonly used for short-distance travel, especially by school children, college students, office workers, farmers, and postmen. It could be very appropriate for smaller, aged populations. It is

possible to run it for free. This scooter is unique in that it does not use valuable fossil oil, thus saving foreign currency cores. It is environmentally sustainable, low-cost, and pollutant-free, since it emits no pollution. Furthermore, it is practically noiseless and can be recharged using an AC converter in the event of a fan

REFERENCES

- [1] Rabiatuladawiah Abu Hanifah, Siti Fauziah Toha, Noor HazrinHani Mohamad Hanif & Nor Azam Kamisan, *Electric Motorcycle Modeling for Speed Tracking and Range Travelled Estimation*, IEEE Access.7(2019)26821-26829.
- [2] Juan Jesús Castillo Aguilar, Javier Pérez Fernández, Juan María Velasco García & Juan Antonio Carrillo, *Regenerative Intelligent Brake Control for Electric Motorcycles*, MDPI Energies.10(2017)1-16.
- [3] Yuechao Sun, Man Li & Cong Liao, *Analysis of Wheel Hub Motor Drive Application in Electric Vehicles*, MATEC Web of Conferences. 100(2017)1-6.
- [4] Najmuddin Jamadar, Suhani Jamadar, Abhilasha Kumbhar, Shital Tanvandkar, Manali Patil & Sourabh Zagde, *Retrofitting of Existing Scooter into Hybrid Electric Scooter*. Journal of Automation and Automobile Engineering, 4(2019)6-13.
- [5] Chai Haibo, Yan Zhiguo & Kuang Mingwei, *Development status of electric vehicle drive motors*, Small & Special Electrical Machines. 41(2013)52-57.
- [6] Luo Longfei & Yuan Shouhua, *Application overview of electric vehicle drive motor and its control system*, Automobile Applied Technology. 4(2014)5-7.
- [7] Liu Jinfeng, Zhang Xueyi & Hu Jianlong, *Development prospect of electric vehicle drive motor*, Agricultural Equipment & Vehicle Engineering. 50(2012)35-38.
- [8] Santiago J, Bernhoff H, Ekergrd B, et al. *Electrical motor drive lines in commercial all-electric vehicles: a review*, IEEE Trans Veh Technol. 61(2012)475-484.
- [9] Yang Y P, Luh Y P & Cheng C H, *Design and control of axial flux brushless DC wheel motors for electric vehicles-part I: multi-objective optimal design and analysis*, IEEE Transaction on Magnetics. 40(2004)1873-1882.
- [10] Lin W C, Lin C L, Hsu P M & Wu M T, *Realization of anti-lock braking strategy for electric scooters*, IEEE Trans. Ind. Electron. 60(2014)2826-2833.
- [11] .Lai Y S & Lin Y K *Design and implementation of digital-controlled bi-directional converter for scooter applications*, In Proceedings of the 2013 IEEE 10th International Conference on Power Electronics and Drive Systems. (2013)271-276.
- [12] Guarisco M, Bouriot B, Ravey A & Bouquain D, *Power train energy management for Hybrid Electric Scooter*, IEEE Transportation Electrification Conference and Expo. (2014)1-4.